



e-LOOP Diagnostics Remote Reference

This document acts as a quick reference guide for the diagnostic's remote settings for the e-loop. It briefly describes what each menu item represents. For further detail, the diagnostics remote manual should be referenced.



Op Mode

• e-loop operation mode (Exit, Presence, Parking).

Trip Value.

 Magnetometer measurement value that measurement must be greater than for a magnetometer detection.

X Axis

• Percentage that the x-axis (left to right) is used for a magnetometer measurement.

Y Axis

• Percentage that the y-axis (front to back) is used for a magnetometer measurement.

Z Axis

• Percentage that the z-axis (up and down) is used for a magnetometer measurement.

Mag Speed

- Whether the magnetometer uses an average of the last 10 measurements or a single measurement when determining a nonmagnetometer detection.
- Using the average results in a slower detection release.

Low Battery

• The voltage trip level used to determine that the battery is getting low.

Diagnostics

The current e-loop state is shown on the diagnostics menu entry.

- Current detection status (whether a vehicle is detected or not).
- Radar mode status (Whether the system is currently in radar-only mode).

Reading

• The latest magnetometer measurement value.

Trip Value

 The magnetometer measurement level for detection.

Temperature

The current temperature of the magnetometer in °C.

Ban

How many e-loop readings the auto compensation is turned off for?

Reset

Last known reset cause.

RSSI

• The radio signal strength between the diagnostics remote and the connected e-loop in dBm.

Calibrate

Calibrate or uncalibrate the e-loop without using the Magnet.





Device Test

The device test checks the sensors and peripherals to make sure that they are working correctly.

 Refer to the test mode reference card for more information on errors during this test.

RSSI Check

 Initiates a radio connection check between the e-loop and it's paired receiver.

Radar settings

Release Trip

• The magnetometer measurement level that magnetometer measurement must be below to unlatch the e-loop.

Start Len

 The distance in meters that the radar will start measuring from, anything before this distance is considered a detection dead zone.

Measure Len

• The distance in meters that the radar will measure from the radar start length.

Radar Trip

 Radar measurement level that a radar measurement must cross for a detection to occur.

Radar Confirm

 Sets whether the system requires the radar to confirm the magnetometer detection when a vehicle is being detected by the eloop.

Radar Int

• How often in seconds the radar checks the detection of a vehicle is correct.

Advanced Radar

Wait Time

• How often the system checks the radar when in radar only mode.

Park Wait Time

 How long the system waits between a magnetometer detection, and confirming the detection with the radar when the e-loop is set to parking mode.

Radar Read

Reads the radar and reports whether the radar is detecting or not detecting.

Radar read true reports that a vehicle is detected.

Radar read false reports that no vehicle is detected.

Device info

Software build date

Date the software that is used in the connected e-loop was built.

Software version

The version number of the software in the connected e-loop.